

#### **CEGAR** and Predicate Abstraction

Dr. Liam O'Connor CSE, UNSW (for now) Term 1 2020

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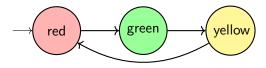
- To know that properties that hold for our abstractions hold for our model true for all  $\varphi \in \mathsf{ACTL}$ .
- To know that when our properties don't hold for our abstractions, they don't hold for our model — not true in general!

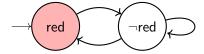
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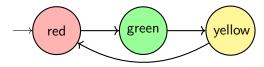
We need to pick the abstraction **based on** the properties we care about, and if necessary change our abstraction on the fly based on the results we see.

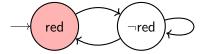




Consider the following ACTL formulae:

• AG (red  $\Rightarrow$  AX  $\neg$ red)

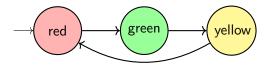


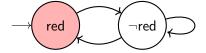


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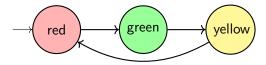


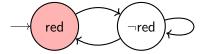


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We know that if  $A \sqsubseteq C$  then  $(A \models \varphi) \Rightarrow (C \models \varphi)$  for  $\varphi \in ACTL$ , but what about if  $A \not\models \varphi$ ?

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## Counterexamples

#### Note

If  $A \not\models \varphi$  for some  $\varphi \in \mathsf{ACTL}$ , then there exists a run that serves as a *counterexample* to the formula  $\varphi$ .

• If  $A \not\models \varphi$ , that tells us either that  $C \not\models \varphi$  or that our abstraction is not precise enough — the counterexample will be *spurious*.

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- Our approach: To check if our counterexample is spurious, convert it to a concrete run ∈ C.

Let  $\alpha$  be our abstraction mapping  $Q_C \to Q_A$  and our run be  $q_0q_1q_2\dots$ . We apply the mapping in reverse,  $\alpha^{-1}$ , and try to find a concrete run starting from our initial state  $I_C$  according to transition relation  $\delta_C$ :

$$S_0 = I_C \cap \alpha^{-1}(q_0)$$
  
 $S_1 = \delta_C(S_0) \cap \alpha^{-1}(q_1)$   
 $S_2 = \delta_C(S_1) \cap \alpha^{-1}(q_2)$  etc..

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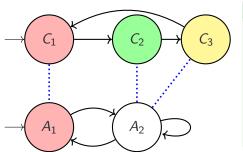
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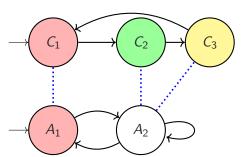
#### Example

 $AG (red \Rightarrow AX AX red)$ 

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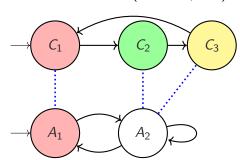


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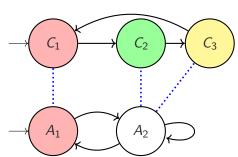
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**AG** (red 
$$\Rightarrow$$
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**Counterexample:**  $A_1A_2A_2$   
 $\alpha^{-1}(A_1A_2A_2)$   
 $= \{C_1\}\{C_2, C_3\}\{C_2, C_3\}$ 

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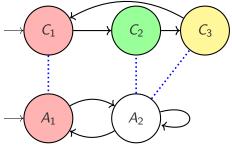
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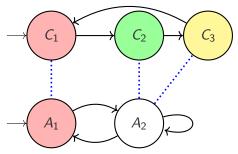


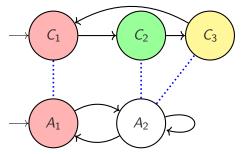
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**AG** (red  $\Rightarrow$  **AX AX** red) **Counterexample:**  $A_1A_2A_2$   $\alpha^{-1}(A_1A_2A_2)$   $= \{C_1\}\{C_2, C_3\}\{C_2, C_3\}$ There is a run  $C_1 \xrightarrow{\delta_C} C_2 \xrightarrow{\delta_C} C_3$  $\therefore$  **Not spurious**.

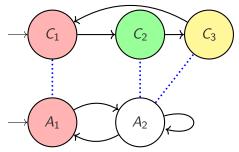


 $\textbf{AG} \; (\mathsf{red} \Rightarrow \textbf{AX} \; \textbf{AX} \; \textbf{AX} \; \mathsf{red})$ 

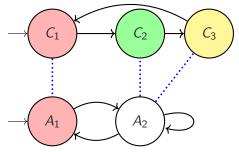




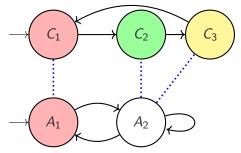
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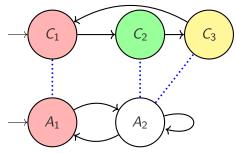
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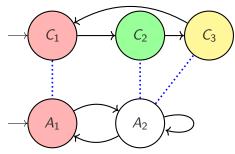


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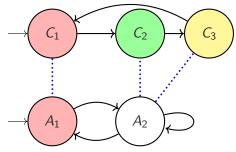


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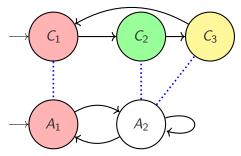


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There is no concrete run — this counterexample is spurious. Our abstraction is too imprecise.

#### **Definition**

An abstraction mapping  $\alpha$  generates an equivalence relation on states  $\equiv_{\alpha}$  where  $q \equiv_{\alpha} q' \Leftrightarrow \alpha(q) = \alpha(q')$ .

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```
Consider two abstractions \alpha: Q_C \to Q_A and \alpha': Q_C \to Q_B.
We say that \alpha' refines \alpha iff \equiv_{\alpha'} \subseteq \equiv_{\alpha}.
Similarly, we say \alpha' strictly refines \alpha iff \equiv_{\alpha'} \subsetneq \equiv_{\alpha}
```

#### **Informal Notion**

We previously considered abstractions as grouping together concrete states into equivalence classes. We can refine abstractions by splitting those equivalence classes.

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We will split this class into two sets:

**1** Those that follow directly from the previous state:  $\alpha^{-1}(q_i) \cap \delta_C(S_{i-1})$ 

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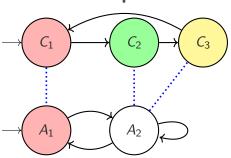
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The resulting classes will form the new, refined abstraction of our model. If both of these sets are non-empty, we split the state  $q_i$  into two states, one for each set.

### Example



**AG** (red  $\Rightarrow$  **AX AX AX** red) **Counterexample:**  $A_1A_2A_2A_2$ 

$$S_0 = I_C \cap \alpha^{-1}(A_1) = \{C_1\} \cap \{C_1\} = \{C_1\}$$

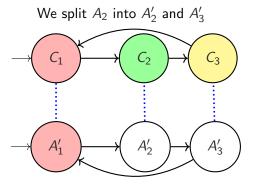
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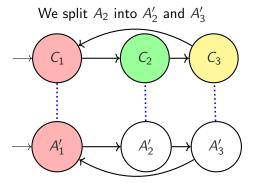
 $\alpha^{-1}(A_2) = \{C_2, C_3\}$ . We have to split this into those that follow from  $S_0$  ( $\{C_2\}$ ) and those that don't ( $\{C_3\}$ ).

# **After Splitting**



We now have an abstraction that does not exhibit our spurious counterexample, but the state space has increased.

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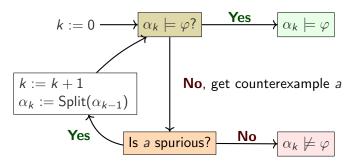


We now have an abstraction that does not exhibit our spurious counterexample, but the state space has increased.

In fact, it's impossible to refine this further, why?

### **CEGAR**

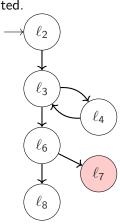
This technique gives us an approach called Counterexample Guided Abstraction Refinement (CEGAR). We have a starting abstraction  $\alpha_0$  and an ACTL formula  $\varphi$ :



# **C** Programs

Objective: Prove that our assertion is never violated.

```
int main() {
   int i = 0, n = 0;
   while (i < n) {
       i++;
   }
   if (i < n)
      assert(false);
}</pre>
```



Need to check reachability, but can we simplify the state space first?

### **Predicate Abstraction**

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A *predicate abstraction* of a program is a version of the program with the same control flow graph, where all variables are replaced with boolean overapproximations.

Booleans can be true, false, or \* (nondeterministically true or false).

### Basic PA

To start with, let's try using i < n as our only predicate:

```
int main() {
int i = 0, n = 0;
while (i < n) {
    i++;
}
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we want our boolean program to be an abstraction.

### Requirement

If a location is not reachable in the abstraction, it is not reachable in the concrete program.

### Basic PA

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```
int main() {
                                     int main() {
      int i = 0, n = 0;
                                        int b = false;
2
      while (i < n) {
                                        while (b) {
         i++:
                                           b = b?*:false;
      }
5
                                  5
      if (i < n)
                                        if (b)
        assert(false);
                                           assert(false);
7
                                     }
```

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   while (i < n) {
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   while (b) {
      i++;
      if (i < n)
      assert(false);
   }
}</pre>
int b = false;
   while (b) {
      b = b?*:false;
   }
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we want our boolean program to be an abstraction.

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If a location is not reachable in the abstraction, it is not reachable in the concrete program.

Now let's try using i < 2 and n >= 3 as our only predicates:

```
int main() {
int i = 0, n = 0;
while (i < n) {
    i++;
}
if (i < n)
assert(false);
}</pre>
```

What do we use for the ?? It must overapproximate i < n.

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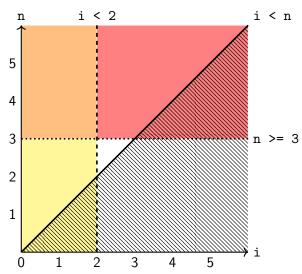
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int main() {
   int main() {
   int i = 0, n = 0;
   while (i < n) {
      if (i < n)
      assert(false);
   }
   int main() {
   int main() {
   int b1 = true, b2 = false;
   while (??) {
      b1 = b1?*:false;
      }
   if (i < n)
      assert(false);
      assert(false);
   }
}</pre>
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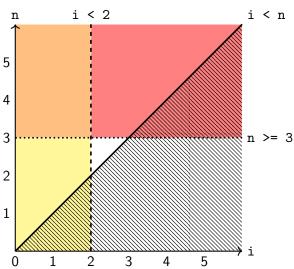
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      while (i < n) {
                                        while (??) {
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        i++:
                                          b1 = b1?*:false;
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      if (i < n)
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                                     }
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What do we use for the ?? It must overapproximate i < n.

## **Abstract Condition**



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The only overapproximation is  $\neg (i < 2 \land n \ge 3)$  i.e. ! (b1 && b2)

```
int main() {
                                     int main() {
     int i = 0, n = 0;
                                       int b1 = true, b2 = false;
     while (i < n) {
                                       while (!(b1 && b2)){
3
        i++;
                                          b1 = b1?*:false;
5
                                 5
     if (i < n)
                                       if (!(b1 && b2))
        assert(false);
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7
                                    }
```

The abstraction with no predicates has all states reachable:

How do we find out what predicates to add?

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### **Example (Abstract Counterexample)**

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Both can't be true simultaneously. This path is spurious.

### **Craig's Interpolation Theorem**

If we have two predicates P(x) and Q(y) such are contradictory (i.e.  $\neg(P(x) \land Q(y))$ ), then there exists a predicate  $I(x \cap y)$  which:

- is implied by P(x), i.e.  $P(x) \Rightarrow I(x \cap y)$ , and
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Sequence of program locations

$$\ell_1\ell_2\ell_3\dots\ell_k$$

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$$\downarrow$$
Sequence of predicates
 $\pi_1\pi_2\pi_3\dots\pi_k$ 

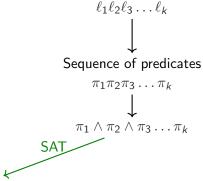
Sequence of program locations



Sequence of predicates

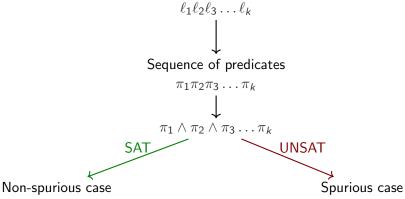
$$\begin{array}{c}
\pi_1 \pi_2 \pi_3 \dots \pi_k \\
\downarrow \\
\pi_1 \wedge \pi_2 \wedge \pi_3 \dots \pi_k
\end{array}$$

Sequence of program locations

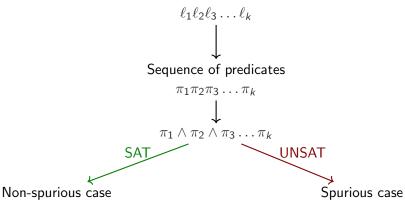


Non-spurious case

Sequence of program locations



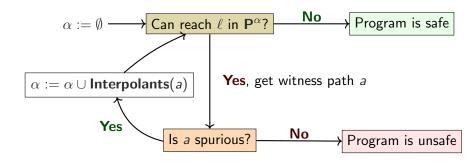
Sequence of program locations



There exists interpolants  $l_1 l_2 l_3 \dots l_{k-1}$ 

# **CEGAR** for C Programs

Let  ${\bf P}$  be our program,  $\alpha$  be our predicate set, and  ${\bf P}^{\alpha}$  be the predicate abstraction of  ${\bf P}$  using  $\alpha$ . The location  $\ell \in {\bf P}$  is our bad state we want to avoid (assertion failure).



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### On C programs

- (Effectively) infinite amount of states
- ... No guarantee of termination
- When it terminates it is both sound (in that it always finds errors if they exist) and complete (it will not provide spurious errors).

# **Bibliography**

CEGAR is used in SLAM/SDV (Microsoft), BLAST (Berkeley) and CBMC (Oxford).

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